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RareBooksClub. Paperback. Book Condition: New. This item is printed on demand. Paperback. 44 pages. Original publisher: Golden, Colo. : National Renewable Energy Laboratory, 1999. OCLC Number: (OCoLC)180205866 Subject: Hybrid electric vehicles -- Research. Excerpt: . . . Figures 11 and 12 show the results of training a neural network with one time delay. The driving cycle fuds13a was employed for training, testing and validation. Of the 6105 data points of this cycle, 2399 points, evenly distributed in chronological sequence, were used for training and testing, and the network was validated upon all the 6105 points. Figure 11 shows the neural network performance on voltage prediction and Figure 12 shows the performance on current prediction. Figure 11-( A ) shows the predicted and actual voltage on the time axis. The prediction error is shown in Figure 11-( B ). Figure 11-( C ) is a plot of the actual voltage versus the predicted voltage. The red line indicates 100 accuracy of prediction. Clearly, the network does a reasonable job of voltage 1 prediction. The average prediction error is 0. 27 and the MSE is nearly zero. However, Figure 12 shows that the prediction of current can be improved further. The average prediction error is 1. 47 and the mean squared error ( MSE ) is 0. 12, while the R-squared error is 0. 96. The improvement of performance with fewer time delay elements strongly suggests that a static model could be more accurate. It is possible that the dynamic element of the model was captured in the SOC algorithm, used in conjunction with the neural network. It was therefore decided to develop static neural networks. 1 The percent error was measured relative to the prediction range, as the ratio of the difference between the target and predicted values to the prediction...



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