

Advanced robot control



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ADVANCED ROBOT CONTROL



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paperback. Book Condition: New. Ship out in 2 business day, And Fast shipping, Free Tracking number will be provided after the shipment. Pages Number: 459 Publisher: Higher Education Press Pub. Date :2007-5-1. This book from the control point of a systematic introduction to the basics of robotics and the current state of development. The book is divided into 12 chapters. from Basics. control structures. articles and papers constitute advanced control. Basics series focuses on joint robot kinematics. motion planning and dynamic. Among them. the kinematic part of the staff from the coordinate transformation. describes the establishment of forward kinematics. inverse kinematics. and robotics to solve the differential movement and so on. Chapter focuses on the robot control architecture of sensor technology. position control and force control. Research in the field for the robot dynamics and control of major research. advanced control of article describes the sensor fusion. visual control. coordination and control. mobile robotics. intelligent control methods. Book a tandem joint robot-based. taking into account the mobile robot control problem. This book combines theory and application oriented. and strive to enable the reader to quickly grasp the robot control technology. an understanding of control of the main research directions. This book can be used as control science and engineering. computers and other disciplines. graduate and advanced undergraduate textbook. but also as scientists and engineers of the reference books. Contents: The Basics Chapter 1 Introduction 1.1 The basic concept of the robot development process 1.2 1.3 robotics field of study the basic structure of the robot's features and the basic method of robot control 1.4 1.4.1 1.4.2 Classification according to the amount of control under the control algorithms classified 1.5 an important area of ??academic journals and conferences About References Exercises Chapter 2 robot kinematics position and attitude of the said 2.1...



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